

# **Technical data sheet**

MP27BUS°

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 8 m<sup>2</sup>
- Torque motor 40 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- with connecting terminals
- Communication via Belimo MP-Bus
- Conversion of sensor signals



## **Technical data**

	<b>N 1 1 1</b>	
Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	4 W
	Power consumption in rest position	1.6 W
	Power consumption for wire sizing	7 VA
	Connection supply / control	Terminals 4 mm <sup>2</sup> (cable Ø410 mm, 4-wire)
unctional data	Torque motor	40 Nm
	Torque variable	25%, 50%, 75% reduced
	Communicative control	MP-Bus
	Operating range Y	210 V
	Input Impedance	100 kΩ
	Options positioning signal	Open/close
		3-point (AC only)
		Modulating (DC 032 V)
	Operating range Y variable	Start point 0.530 V
	1 0 0	End point 2.532 V
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.58 V
		End point 2.510 V
	Position accuracy	±5%
	Direction of motion motor	selectable with switch 0/1
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) /
		1 (cw rotation)
	Direction of motion variable	electronically reversible
	Manual override	with push-button, can be locked
	Angle of rotation	Max. 95°
	Angle of rotation note	can be limited on both sides with adjustable
		mechanical end stops
	Running time motor	150 s / 90°
	Running time motor variable	75290 s
	Adaptation setting range	manual
	Adaptation setting range variable	No action
	1 5 5	Adaptation when switched on
		Adaptation after pushing the gear
		disengagement button
	Override control	MAX (maximum position) = 100%
		MIN (minimum position) $= 0\%$
		ZS (intermediate position, AC only) = 50%
	Override control variable	MAX = (MIN + 32%)100%
		MIN = 0%(MAX - 32%)
		ZS = MINMAX
	Sound power level, motor	45 dB(A)
	Mechanical interface	Universal shaft clamp reversible 1226.7 mm
	Position indication	Mechanically, pluggable
Safety	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
,	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP54



# **Technical data**

Safety	Degree of protection NEMA/UL	NEMA 2
-	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL60730-1A, UL60730-2- 14 and CAN/CSA E60730-1:02
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in
		any case
	Mode of operation	Туре 1
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	3
	Ambient temperature	-3050°C
	Storage temperature	-4080°C
	Ambient humidity	Max. 95% r.H., non-condensing
	Servicing	maintenance-free
Weight	Weight	1.8 kg

Safety notes



• The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.

- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation
  or aggressive gases interfere directly with the actuator and that is ensured that the
  ambient conditions remain at any time within the thresholds according to the data
  sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features	
Mode of operation	Conventional operation: The actuator is connected with a standard modulating signal of 010 V and drives to the position defined by the positioning signal. The measuring voltage U serves for the electrical display of the actuator position 0.5100% and as slave control signal for other actuators. Operation on Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
Parametrisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
Simple direct mounting	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
Manual override	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.

Rotary actuator, modulating, communicative, AC/ DC 24 V, 40 Nm, Communication via Belimo MP-Bus



Product features	
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. $\underbrace{\bigvee_{1}^{0}}_{1} \frac{Y = 0 \ V  ccw}_{V = 0 \ V} \underbrace{\bigvee_{1}^{0}}_{V \to V} \underbrace{\bigvee_{1}^{0}}_{V \to V} \underbrace{\bigvee_{1}^{0}_{V \to V} \underbrace{\bigvee_{1}^{0}}_{V \to V} \underbrace{\bigvee_{1}^{0}}_{V \to V} \underbrace{\bigvee_{1}^{0}_{V \to V} \underbrace{\bigvee_{1}^{0}}_{V \to V} \underbrace{\bigvee_{1}^{0}}_{V \to V} \underbrace{\bigvee_{1}^{0}_{V \to V} \underbrace{\bigvee_{1}^{0}}_{V \to$
Adaption and synchronisation	An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

### Accessories

Gateways       Gateway MP zu BACnet MS/TP       UK24BAC         Gateway MP to Modbus RTU       UK24MOD         Gateway MP to LonWorks       UK24LON         Gateway MP to KNX       UK24EIB         Description       Type         Auxiliary switch 1 x SPDT add-on       S1A         Auxiliary switch 2 x SPDT add-on       S2A
Gateway MP to LonWorks     UK24LON       Gateway MP to KNX     UK24EIB       Description     Type       Auxiliary switch 1 x SPDT add-on     S1A
Gateway MP to KNX     UK24EIB       Description     Type       Electrical accessories     Auxiliary switch 1 x SPDT add-on     S1A
Description     Type       Electrical accessories     Auxiliary switch 1 x SPDT add-on     S1A
Electrical accessories         Auxiliary switch 1 x SPDT add-on         S1A
Auxiliary switch 2 x SPDT add-on S2A
Auxiliary switch 2 x SPDT add-on, grau S2A/300 GR
Auxiliary switch 2 x SPDT add-on, grau S2A/500 GR
Feedback potentiometer 140 Ω add-on P140A
Feedback potentiometer 140 Ω add-on, grau P140A GR
Feedback potentiometer 200 Ω add-on P200A
Feedback potentiometer 500 Ω add-on P500A
Feedback potentiometer 500 Ω add-on, grau P500A GR
Feedback potentiometer 1 kΩ add-on P1000A
Feedback potentiometer 1 kΩ add-on, grau P1000A GR
Feedback potentiometer 2.8 kΩ add-on P2800A
Feedback potentiometer 2.8 kΩ add-on, grau P2800A GR
Feedback potentiometer 5 kΩ add-on P5000A
Feedback potentiometer 5 kΩ add-on, grau P5000A GR
Feedback potentiometer 10 kΩ add-on P10000A
Feedback potentiometer 10 kΩ add-on, grau P10000A GR
Positioner for wall mounting CRP24-B1
Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin service socket for ZK1-GEN Belimo device
Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for ZK2-GEN connection to MP/PP terminal
Connecting board MP-Bus for wiring boxes EXT-WR-FPMP ZFP2-MP
MP-Bus power supply for MP actuators ZN230-24MP
Description Type
Mechanical accessories         Actuator arm for standard shaft clamp         AH-GMA
Ball joint suitable for damper crank arm KH8 / KH10 KG10A
Damper crank arm Slot width 8.2 mm, clamping range Ø1425 mm KH10
Anti-rotation mechanism 230 mm, Multipack 20 pcs. Z-ARS230
Mounting kit for linkage operation for flat installation ZG-GMA
Base plate extension for GMA to GM, Multipack 20 pcs. Z-GMA

Accessories

Rotary actuator, modulating, communicative, AC/ DC 24 V, 40 Nm, Communication via Belimo MP-Bus

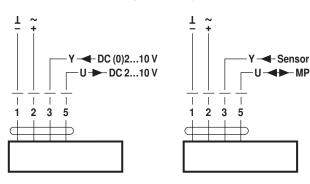


	Description	Туре
	Position indicator, Multipack 20 pcs.	Z-PI
	Terminal protection IP54, Multipack 20 pcs.	Z-TP
	Description	Туре
Service Tool	s Service Tool, with ZIP-USB function	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C
Electrical installation		
Notes	<ul> <li>Connection via safety isolating transformer.</li> <li>Parallel connection of other actuators possible. Observe the performance data.</li> </ul>	

### Wiring diagrams

AC/DC 24 V, modulating

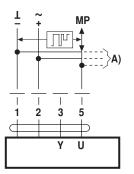
Operation on the MP-Bus



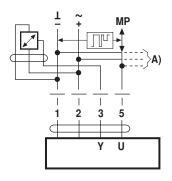
### **Functions**

#### Functions when operated on MP-Bus

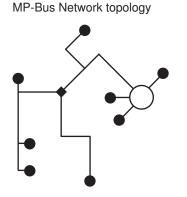
Connection on the MP-Bus



Connection of active sensors



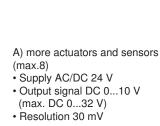
A) more actuators and sensors (max.8)

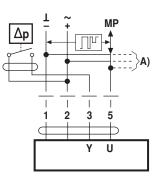


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary

• no terminating resistors required

Connection of external switching contact





A) more actuators and sensors (max.8)

Switching current 16 mA @ 24 V

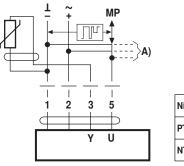
• Start point of the operating range must be parameterised on the MP actuator as  $\ge 0.5 \text{ V}$ 

Rotary actuator, modulating, communicative, AC/ DC 24 V, 40 Nm, Communication via Belimo MP-Bus



## **Functions**

Connection of passive sensors

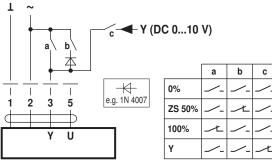


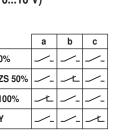
Ni1000	–28+98°C	8501600 Ω <sup>2)</sup>
PT1000	–35+155°C	8501600 Ω <sup>2)</sup>
NTC	-10+160°C <sup>1)</sup>	200 Ω60 kΩ <sup>2)</sup>

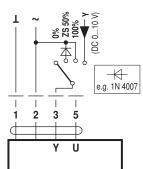
A) more actuators and sensors (max.8) 1) Depending on the type 2) Resolution 1 Ohm

### Functions with basic values (conventional mode)

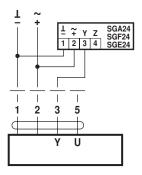
Override control with AC 24 V with relay contacts

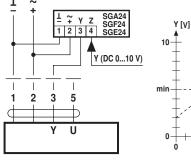




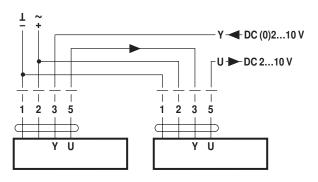


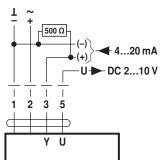
Control remotely 0...100% with Minimum limit with positioner SG... positioner SG..



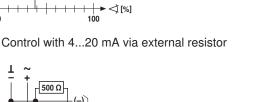


Follow-up control (position-dependent)





Override control with AC 24 V with rotary switch



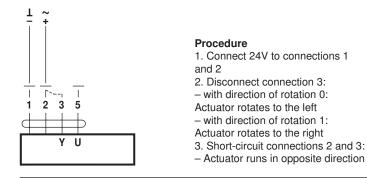
#### Caution:

The operating range must be set to DC 2...10 V. The 500  $\Omega$  resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V



# **Functions**

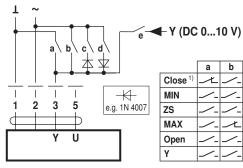
#### Functional check



#### Functions for devices with specific parameters (Parametrisation necessary)

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Override control and limiting with AC 24 V with relay contacts



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Control open/close

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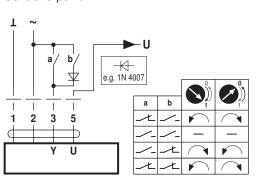
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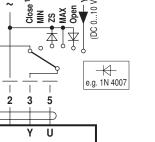


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Override control and limiting with AC 24 V with rotary switch



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1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

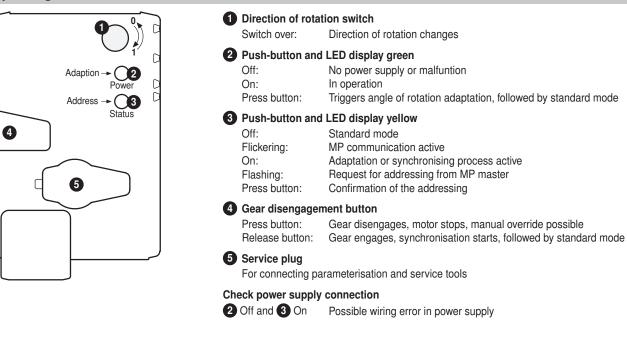
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Rotary actuator, modulating, communicative, AC/ DC 24 V, 40 Nm, Communication via Belimo MP-Bus



## **Operating controls and indicators**

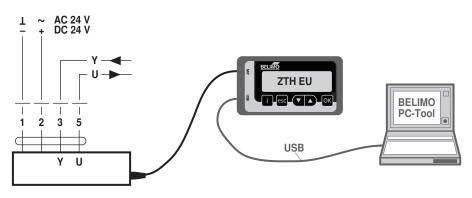


Service

Service Tools connection

The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool



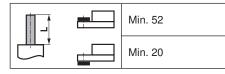
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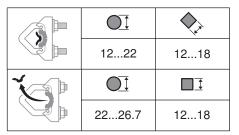
4...10

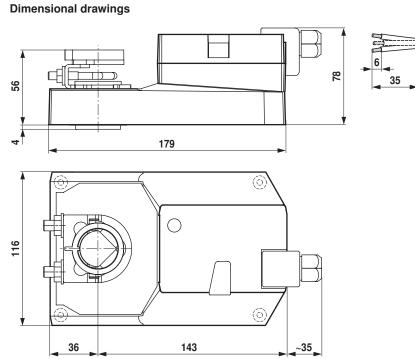
# **Dimensions** [mm]

## Spindle length



### **Clamping range**





### **Further documentation**

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology