

Communicative RobustLine damper actuator for adjusting dampers in industrial plants and in technical building installations

- Air damper size up to approx. 2 m<sup>2</sup>
- Torque motor 10 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus
- Optimum protection against corrosion and chemical influences, UV radiation, damp and condensation


**Technical data**

<b>Electrical data</b>	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V	
	Power consumption in operation	3.5 W	
	Power consumption in rest position	1.4 W	
	Power consumption for wire sizing	6 VA	
	Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup> (halogen-free)	
	Parallel operation	Yes (note the performance data)	
	<b>Functional data</b>	Torque motor	10 Nm
		Torque variable	25%, 50%, 75% reduced
Communicative control		MP-Bus	
Operating range Y		2...10 V	
Input Impedance		100 kΩ	
Options positioning signal		Open/close 3-point (AC only) Modulating (DC 0...32 V)	
Operating range Y variable		Start point 0.5...30 V End point 2.5...32 V	
Position feedback U		2...10 V	
Position feedback U note		Max. 0.5 mA	
Position feedback U variable		Start point 0.5...8 V End point 2.5...10 V	
Position accuracy		±5%	
Direction of motion motor		selectable with switch 0/1	
Direction of motion note		Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)	
Direction of motion variable		electronically reversible	
Manual override		with push-button, can be locked	
Angle of rotation		Max. 95°	
Angle of rotation note		can be limited on both sides with adjustable mechanical end stops	
Running time motor		150 s / 90°	
Running time motor variable		43...173 s	
Adaptation setting range		manual	
Adaptation setting range variable		No action Adaptation when switched on Adaptation after pushing the gear disengagement button	
Override control		MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%	
Override control variable		MAX = (MIN + 32%)...100% MIN = 0%...(MAX - 32%) ZS = MIN...MAX	
Sound power level, motor		35 dB(A)	
Mechanical interface		Universal shaft clamp 10...20 mm	
Position indication		Mechanically, pluggable	
<b>Safety</b>		Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)

Technical data

<b>Safety</b>	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP66/67
	Degree of protection NEMA/UL	NEMA 4X
	Enclosure	UL Enclosure Type 4X
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1:02
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Mode of operation	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	4
	Ambient temperature	-30...50 °C
	Storage temperature	-40...80 °C
	Ambient humidity	Max. 100% r.H.
Weight	2.0 kg	

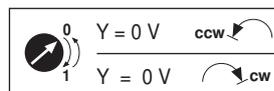
Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- Junction boxes must at least correspond with enclosure IP degree of protection!
- The cover of the protective housing may be opened for adjustment and servicing. When it is closed afterwards, the housing must seal tight (see installation instructions).
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cables must not be removed from the device installed in the interior.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
- The information on chemical resistance refers to laboratory tests with raw materials and finished products and to trials in the field in the areas of application indicated.
- The materials used may be subjected to external influences (temperature, pressure, constructional fixture, effect of chemical substances, etc.), which cannot be simulated in laboratory tests or field trials.
- The information regarding areas of application and resistance can therefore only serve as a guideline. In case of doubt, we definitely recommend that you carry out a test. This information does not imply any legal entitlement. Belimo will not be held liable and will provide no warranty. The chemical or mechanical resistance of the materials used is not alone sufficient for judging the suitability of a product. Regulations pertaining to combustible liquids such as solvents etc. must be taken into account with special reference to explosion protection.
- Flexible metallic cable conduits or threaded cable conduits of equal value are to be used for UL (NEMA) Type 4X applications.
- When used under high UV loads, e.g. extreme sunlight, the use of flexible metallic or equivalent cable conduits is recommended.

Product features

<b>Fields of application</b>	The actuator is particularly suitable for utilisation in outdoor applications and is protected against the following weather conditions: <ul style="list-style-type: none"> <li>- Wood drying</li> <li>- Animal breeding</li> <li>- Food processing</li> <li>- Agriculture</li> <li>- Indoor swimming pools / bathhouses</li> <li>- Rooftop ventilation plant rooms</li> <li>- General outdoor applications</li> <li>- Alternating climate</li> <li>- Laboratories</li> </ul>
<b>Resistances</b>	Noxious gas test EN 60068-2-60 (Fraunhofer Institut ICT / DE) Salt fog spray test EN 60068-2-52 (Fraunhofer Institut ICT / DE) Ammoniac test DIN 50916-2 (Fraunhofer Institut ICT / DE) Climate test IEC60068-2-30 (Trikon Solutions AG / CH) Disinfectant (animals) (Trikon Solutions AG / CH) UV Test (Solar radiation at ground level) EN 60068-2-5, EN 60068-2-63 (Quinel / Zug CH)
<b>Used materials</b>	Actuator housing polypropylene (PP) Cable glands / hollow shaft polyamide (PA) Connecting cable FRNC Clamp / screws in general Steel 1.4404 Seals EPDM Form fit insert aluminium anodised
<b>Mode of operation</b>	Conventional operation: The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. The measuring voltage U serves for the electrical display of the actuator position 0.5...100% and as slave control signal for other actuators. Operation on Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.
<b>Converter for sensors</b>	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
<b>Parametrisable actuators</b>	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
<b>Simple direct mounting</b>	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
<b>Manual override</b>	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).
<b>Adjustable angle of rotation</b>	Adjustable angle of rotation with mechanical end stops. Standard setting 0 ... 90°. The housing cover must be removed to set the angle of rotation.
<b>High functional reliability</b>	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
<b>Home position</b>	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal.



**Product features**

**Adaption and synchronisation** An adaption can be triggered manually by pressing the “Adaption” button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).  
Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).  
The actuator then moves into the position defined by the positioning signal.  
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

**Accessories**

	Description	Type
<b>Gateways</b>	Gateway MP to Modbus RTU	UK24MOD
	Gateway MP zu BACnet MS/TP	UK24BAC
	Gateway MP to LonWorks	UK24LON
	Gateway MP to KNX	UK24EIB
<b>Electrical accessories</b>	<b>Description</b>	<b>Type</b>
	Auxiliary switch 2 x SPDT add-on, grau	S2A GR
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 200 Ω add-on	P200A
	Feedback potentiometer 500 Ω add-on	P500A
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 2.8 kΩ add-on	P2800A
	Feedback potentiometer 5 kΩ add-on	P5000A
Feedback potentiometer 10 kΩ add-on	P10000A	
<b>Service Tools</b>	<b>Description</b>	<b>Type</b>
	Service Tool, with ZIP-USB function	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C

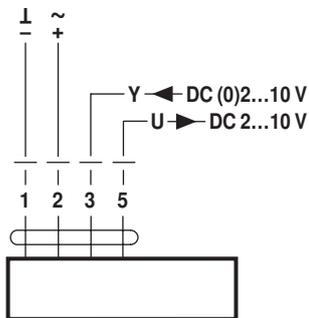
**Electrical installation**

**Notes**

- Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

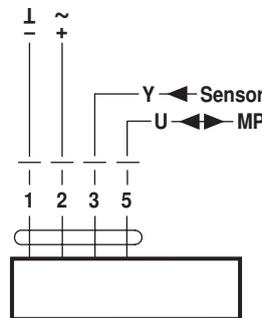
**Wiring diagrams**

AC/DC 24 V, modulating



**Cable colours:**  
1 = black  
2 = red  
3 = white  
5 = orange

Operation on the MP-Bus

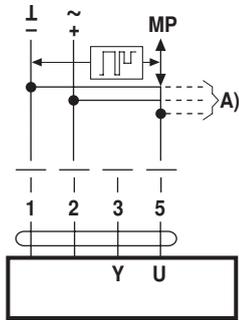


**Cable colours:**  
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Functions

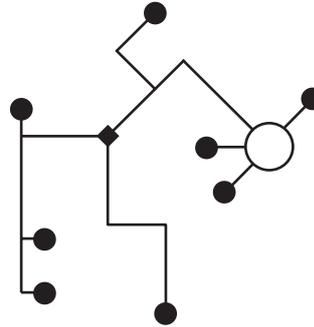
Functions when operated on MP-Bus

Connection on the MP-Bus



A) more actuators and sensors (max.8)

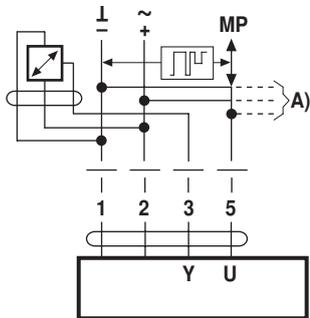
MP-Bus Network topology



There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- no terminating resistors required

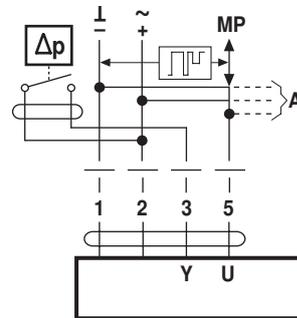
Connection of active sensors



A) more actuators and sensors (max.8)

- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV

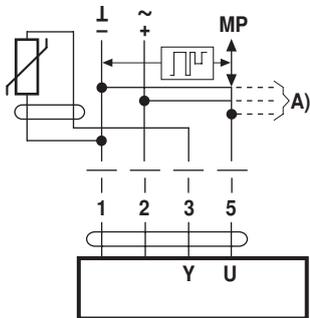
Connection of external switching contact



A) more actuators and sensors (max.8)

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as  $\geq 0.5$  V

Connection of passive sensors



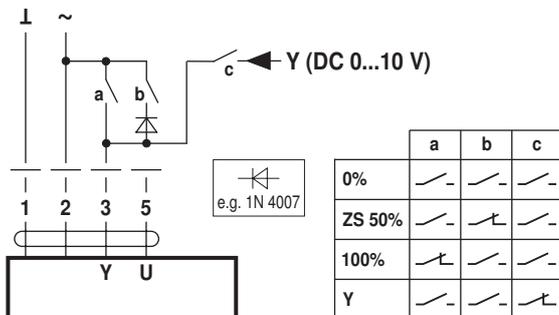
Ni1000	-28...+98 °C	850...1600 $\Omega^2$
PT1000	-35...+155 °C	850...1600 $\Omega^2$
NTC	-10...+160 °C <sup>1)</sup>	200 $\Omega$ ...60 k $\Omega^2$

A) more actuators and sensors (max.8)

- 1) Depending on the type
- 2) Resolution 1 Ohm

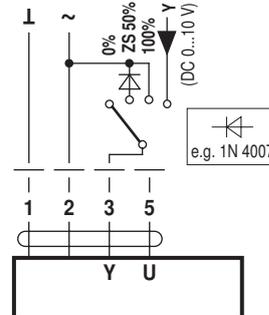
Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts



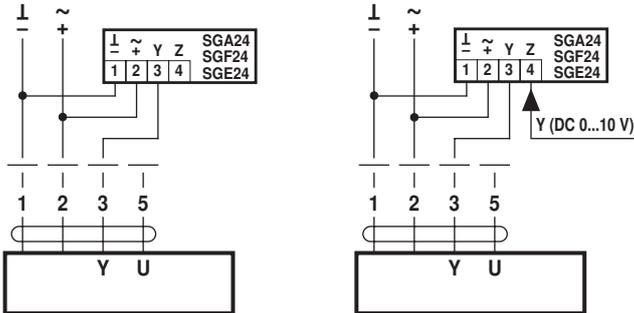
	a	b	c
0%	—	—	—
ZS 50%	—	—	—
100%	—	—	—
Y	—	—	—

Override control with AC 24 V with rotary switch

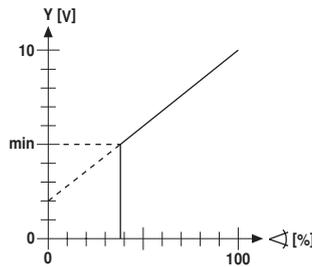


Functions

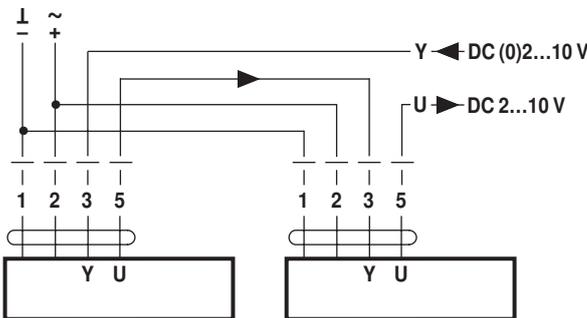
Control remotely 0...100% with positioner SG..  
 positioner SG..



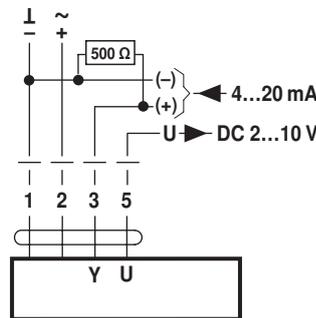
Follow-up control (position-dependent)



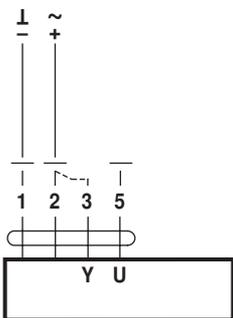
Control with 4...20 mA via external resistor



Functional check



**Caution:**  
 The operating range must be set to DC 2...10 V.  
 The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

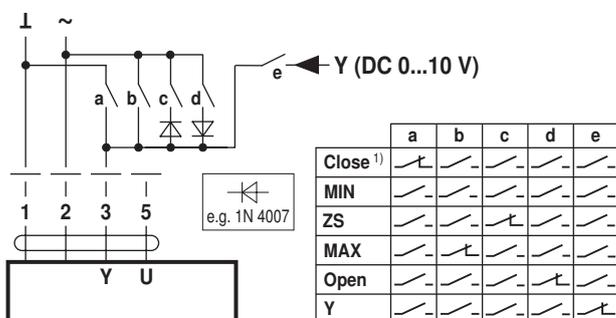


**Procedure**

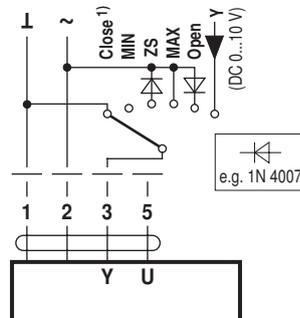
1. Connect 24V to connections 1 and 2
2. Disconnect connection 3:
  - with direction of rotation 0: Actuator rotates to the left
  - with direction of rotation 1: Actuator rotates to the right
3. Short-circuit connections 2 and 3:
  - Actuator runs in opposite direction

Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts



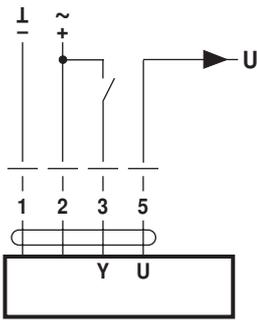
Override control and limiting with AC 24 V with rotary switch



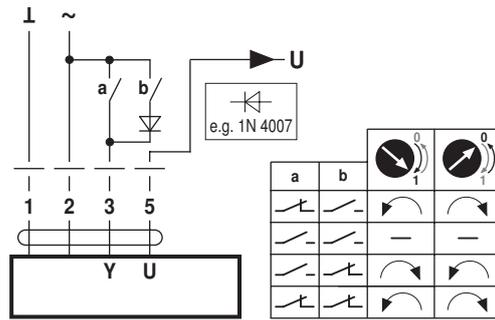
1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

**Functions**

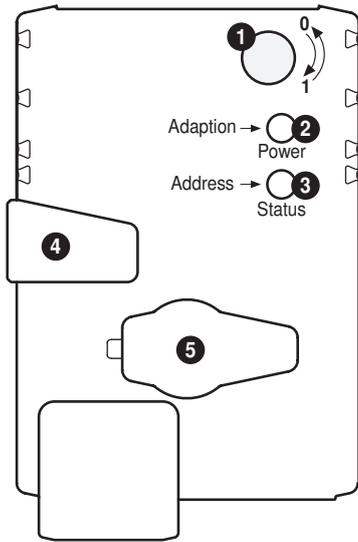
Control open/close



Control 3-point



**Operating controls and indicators**



- 1 Direction of rotation switch**  
Switch over: Direction of rotation changes
- 2 Push-button and LED display green**  
Off: No power supply or malfunction  
On: In operation  
Press button: Triggers angle of rotation adaptation, followed by standard mode
- 3 Push-button and LED display yellow**  
Off: Standard mode  
Flickering: MP communication active  
On: Adaptation or synchronising process active  
Flashing: Request for addressing from MP master  
Press button: Confirmation of the addressing
- 4 Gear disengagement button**  
Press button: Gear disengages, motor stops, manual override possible  
Release button: Gear engages, synchronisation starts, followed by standard mode
- 5 Service plug**  
For connecting parameterisation and service tools

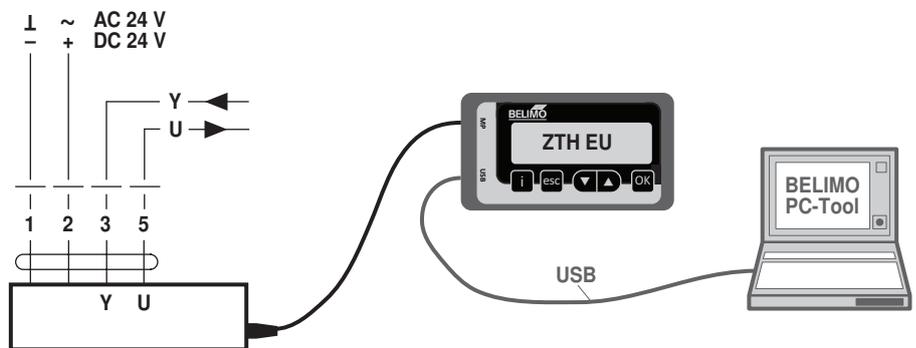
**Check power supply connection**

- 2** Off and **3** On Possible wiring error in power supply

**Service**

**Service Tools connection** The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool



**Dimensions [mm]**

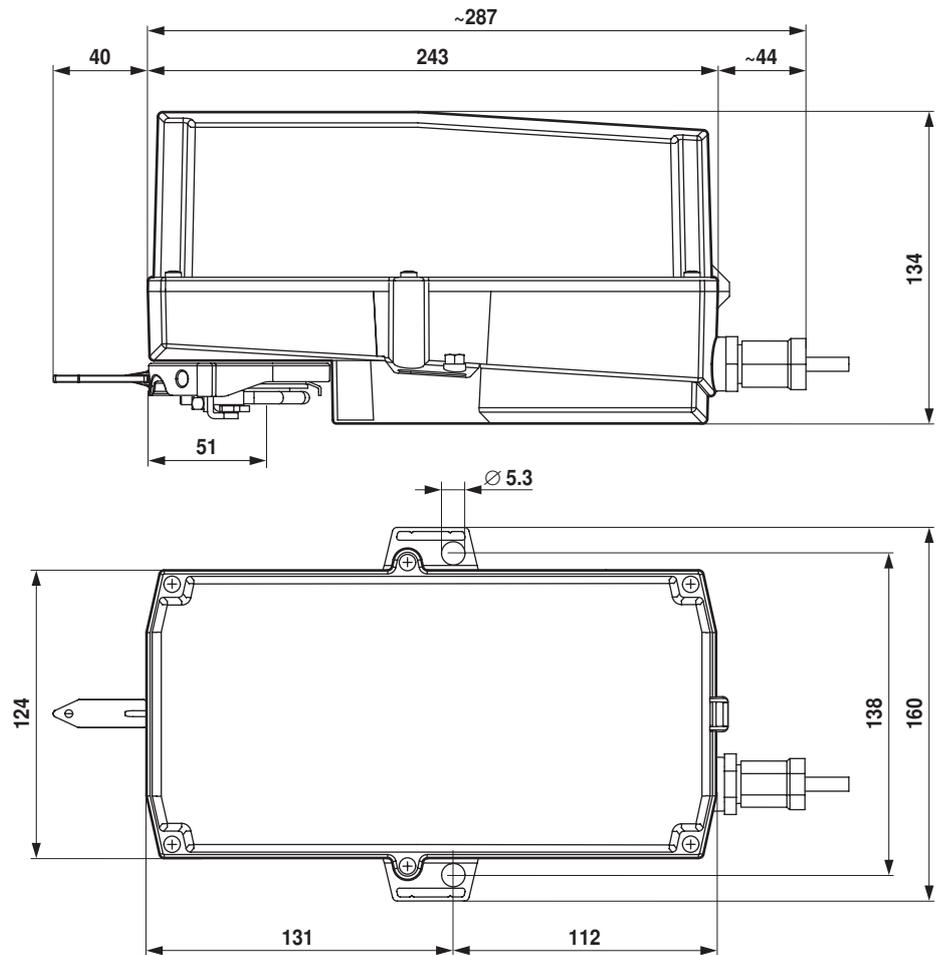
**Spindle length**

	-
	20...58

**Clamping range**

10...20	8...14	10...20

**Dimensional drawings**



**Further documentation**

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology