

Technical data sheet

NRF24A-MP

MP/27BUS

Communicative rotary actuator with fail-safe for ball valves

- Torque motor 10 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Conversion of sensor signals
- Deenergised closed (NC)
- Communication via Belimo MP-Bus



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	7 W
	Power consumption in rest position	3.5 W
	Power consumption for wire sizing	9.5 VA
	Connection supply / control	Cable 1 m, 4 x 0.75 mm ²
	Parallel operation	Yes (note the performance data)
unctional data	Torque motor	10 Nm
	Torque fail-safe	10 Nm
	Communicative control	MP-Bus
	Operating range Y	210 V
	Input Impedance	100 kΩ
	Options positioning signal	Open/close
	optione poolitioning signal	3-point (AC only)
		Modulating (DC 032 V)
	Operating range Y variable	Start point 0.530 V
		End point 2.532 V
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.58 V
		End point 2.510 V
	Position accuracy	±5%
	Direction of motion motor	Y = 0 (0 V = A - AB = 0%)
	Direction of motion fail-safe	Deenergised NC, valve closed $(A - AB = 0\%)$
	Manual override	by means of hand crank and locking switch
	Running time motor	90 s / 90°
	Running time motor variable	40150 s
	Running time fail-safe	<20 s / 90°
	Running time fail-safe note	@ -2050°C / <60 s @ -30°C
	Adaptation setting range	manual (automatic on first power-up)
	Adaptation setting range variable	No action
	radplation botting range variable	Adaptation when switched on
		Adaptation after using the hand crank
	Override control	MAX (maximum position) = 100%
		MIN (minimum position) = 0%
		ZS (intermediate position, AC only) = 50%
	Override control variable	MAX = (MIN + 33%)100%
		MIN = 0%(MAX - 33%)
		ZS = MINMAX
	Sound power level, motor	45 dB(A)
	Position indication	Mechanical
	Service life	Min. 60'000 fail-safe positions
Safety	Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU

Rotary actuator fail-safe, modulating, communicative, AC/DC 24 V, 10 Nm, Communication via Belimo MP-Bus



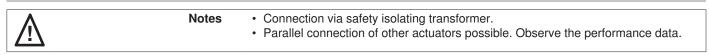
Technical data			
Safety	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
	Certification UL	cULus according to UL60730-1A, UL60730-2- 14 and CAN/CSA E60730-1:02	
	Certification UL note	The UL marking on the actuator depends on the production site, the device is UL-compliant in any case	
	Mode of operation	Type 1.AA	
	Rated impulse voltage supply / control	0.8 kV	
	Control pollution degree	3	
	Ambient temperature	-3050°C -4080°C	
	Storage temperature Ambient humidity	Max. 95% r.H., non-condensing	
	Servicing	maintenance-free	
Weight	Weight	2.0 kg	
Safety notes			
\bigwedge	conditioning systems and must not be especially in aircraft or in any other a	se in stationary heating, ventilation and air- be used outside the specified field of application, airborne means of transport.	
	or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.		
	 Only authorised specialists may carr institutional installation regulations n 	y out installation. All applicable legal or nust be complied during installation.	
	The device may only be opened at the parts that can be replaced or repaired or repair	he manufacturer's site. It does not contain any ed by the user.	
	Cables must not be removed from the second sec	ne device.	
		lectronic components and must not be disposed Ilid regulations and requirements must be	
Product features			
Mode of operation	Conventional operation: The actuator is connected with a standard modulating signal 010 V. The actuator moves the valve to the operating position at the same time as tensioning the return spring. The valve is turned back to the fail-safe position by spring force when the supply voltage is interrupted. Operation on Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.		
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the senso signal via MP-Bus to the higher level system.		
Parametrisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.		
Simple direct mounting	Simple direct mounting on the ball valve with only one screw. The mounting orientatio in relation to the ball valve can be selected in 90° steps.		
Manual override	By using the hand crank the valve can be operated manually and engaged with the locking switch at any position. Unlocking is carried out manually or automatically by applying the operating voltage.		
Adjustable angle of rotation	Adjustable angle of rotation with mech	anical end stops.	
High functional reliability	The set of the factor of the set	uires no limit switches and automatically stops	

NRF24A-MP	Rotary actuator fail-safe, modulating, communicative, AC/DC 24 V, 10 Nm, Communication via Belimo MP-Bus	BELIMO
Product features		
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range. The actuator then moves into the position defined by the positioning signal. Factory setting: Y2 (counter-clockwise rotation).	
Adaption and synchronisation	An adaption can be triggered manually by pressing the "Adaption" b PC-Tool. Both mechanical end stops are detected during the adapti range). Automatic synchronisation after actuating the hand crank is synchronisation is in the home position (0%). A range of settings can be adapted using the PC-Tool (see MFT-P	ion (entire setting programmed. The

Accessories

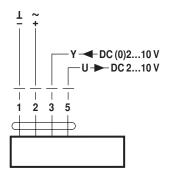
	Description	Туре
Gateways	Gateway MP zu BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD
	Gateway MP to KNX	UK24EIB
	Description	Туре
Electrical accessories	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Connecting board MP-Bus for wiring boxes EXT-WR-FPMP	ZFP2-MP
	MP-Bus power supply for MP actuators	ZN230-24MP
	Description	Туре
Service Tools	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators / VAV controller and HVAC performance devices	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C

Electrical installation



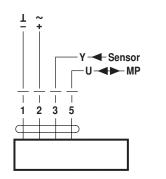
Wiring diagrams

AC/DC 24 V, modulating





Operation on the MP-Bus



Cable colours: 1 = black 2 = red

3 = white

5 = orange

Rotary actuator fail-safe, modulating, communicative, AC/DC 24 V, 10 Nm, Communication via Belimo MP-Bus

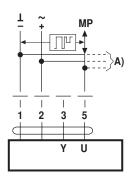
MP-Bus Network topology

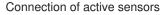


Functions

Functions when operated on MP-Bus

Connection on the MP-Bus





A) additional MP-Bus nodes (max. 8)

A) additional MP-Bus nodes (max. 8)

Supply AC/DC 24 V

(max. DC 0...32 V)

Resolution 30 mV

Ni1000

PT1000

NTC

Output signal DC 0...10 V

–28...+98°C

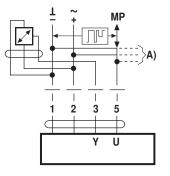
-35...+155°C

-10...+160°C¹

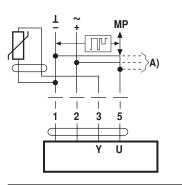
850...1600 Ω²⁾

 $850...1600 \ \Omega^{2)}$

200 Ω...60 kΩ ²⁾

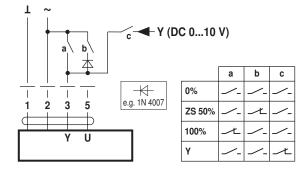


Connection of passive sensors



Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts

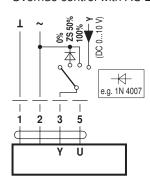


Override control with AC 24 V with rotary switch

A) additional MP-Bus nodes (max. 8)

1) Depending on the type

2) Resolution 1 Ohm



There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary

• no terminating resistors required

Connection of external switching contact

MP

ΥU

יחך

2 3 5

 \subset

A) additional MP-Bus nodes (max. 8)
Switching current 16 mA @ 24 V
Start point of the operating range

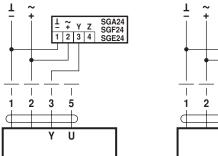
must be parametrised on the MP actuator as ≥ 0.5 V

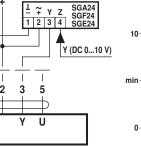
NRF24A-MP • en-gb • 2020-07-21 • subject to changes



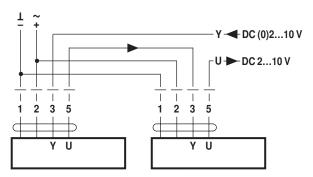
Functions

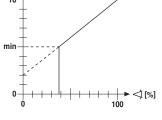
Control remotely 0...100% with Minimum limit with positioner SG..





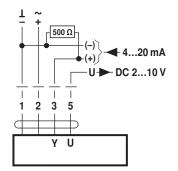
Follow-up control (position-dependent)





Y [V]

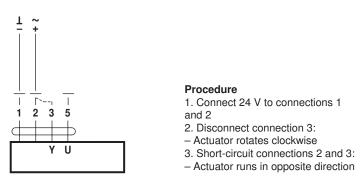
Control with 4...20 mA via external resistor



Caution:

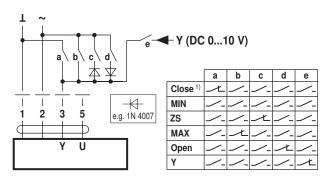
The operating range must be set to DC 2...10 V. The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

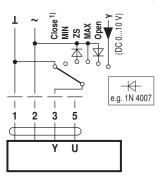
Functional check



Functions for devices with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts





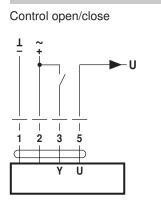
Override control and limiting with AC 24 V with rotary switch

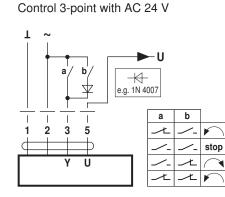
1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

Rotary actuator fail-safe, modulating, communicative, AC/DC 24 V, 10 Nm, Communication via Belimo MP-Bus

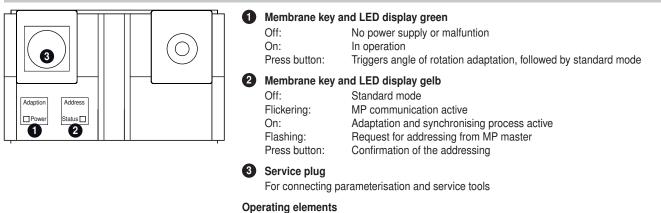


Functions





Operating controls and indicators



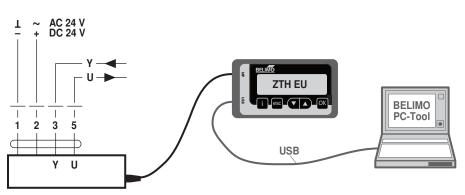
The manual override, locking switch and direction of rotation switch elements are available on both sidesa

Service

Service Tools connection

The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

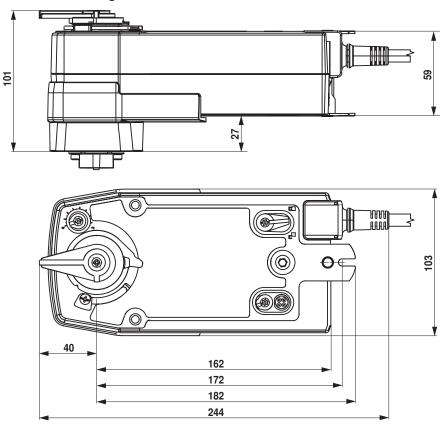
Connection ZTH EU / PC-Tool





Dimensions [mm]

Dimensional drawings



Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology
- The complete product range for water applications
- Data sheets for ball valves
- · Installation instructions for actuators and/or ball valves
- · General notes for project planning